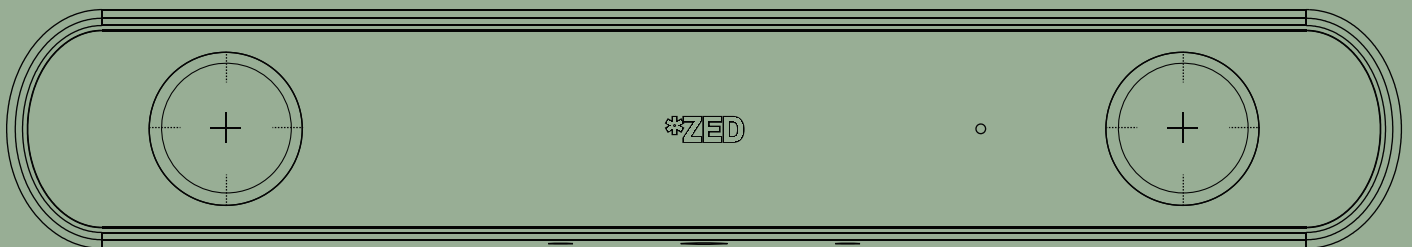


*ZED 2

Datasheet

The ZED 2 is a stereo camera that provides high definition 3D video and neural depth perception of the environment. It has been designed for the most challenging applications, from autonomous navigation and mapping to augmented reality and 3D analytics.



*ZED 2 Overview

Spatial Object Detection

Detect and track object with spatial context. By combining AI and 3D the ZED 2 localizes the objects in space and provides the tools to create the next-generation spatial awareness.

Neural Depth Sensing

The ZED 2 is the first stereo camera that uses neural networks to reproduce human vision, bringing stereo perception to a new level.

All-Aluminum Case

The ZED 2 comes with a more robust all-aluminium enclosure with thermal control that compensates focal length and motion sensors biases

Built-in Sensor Stack

The most extensive sensor stack is available on ZED 2. Together with inertial data, the ZED 2 also captures elevation and magnetic field in real-time

Camera Control

The ZED 2 is a UVC video camera with low level access to the device. It provides control over all the camera parameters such as exposure, gain, sharpness, etc.

Cloud Connected

Monitor and control your camera remotely. Using the dedicated cloud platform, capture and analyze spatial data anywhere in the world. Manage your application remotely and update you camera at an time.

Technical Specifications

Camera

Output Resolution	2x (2208x1242) @15fps 2x (1920x1080) @30fps 2x (1280x720) @60fps 2x (672x376) @100fps
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Field of View	Max. 110°(H) x 70°(V) x 120°(D)
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Interface	USB 3.0/2.0 Integrated 1.2m cable (3.97ft)
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Depth Range	0.3 m to 20 m (0.98ft to 65.61ft)
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Depth Accuracy	< 1% up to 3m (9.84ft) < 5% up to 15m (49.21ft)
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Sensors

Motion	Gyroscope, Accelerometer, Magnetometer
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Environmental	Barometer, Temperature
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Physical

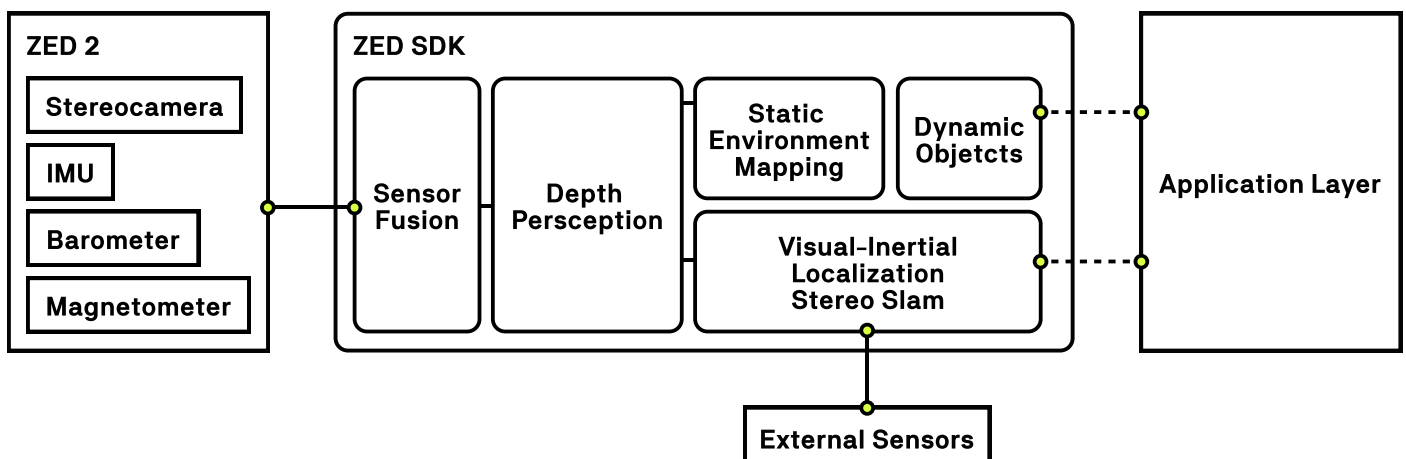
Dimensions	174.9 x 29.8 x 31.9mm (6.89 x 1.18 x 1.25")
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Weight	164g (0.36 lb.)
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Op. Temp.	-10 °C to +45°C (14°F to 113°F)
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Power	380 mA / 5V USB Powered
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Functional SDK Diagram



*ZED 2 Sensors Specifications

Dual Image Sensors

Sensors	
Sensor Type	1/3" 4MP CMOS
Array Size	2688 x 1520 pixels
Pixel Size	2µm x 2µm
Shutter	Electronic synchronized rolling shutter
Output Resolution	2x (2208x1242) @15fps cropping mode 2x (1920x1080) @15/30fps cropping mode 2x (1280x720) @15/30/60fps binning 2x2 mode 2x (662x376) @15/30/60/100fps binning 4x4 mode
Output Format	YUV 4:2:2 - UYVY (8 bits)
Max S/N Ration	38.3 dB
Dynamic Range	64.6 dB
Sensitivity	1900 mV/Lux-sec
Lenses	
Baseline	120mm (4.7")
Focal Length	2.12mm (0.08")
Field of View	Max. 110° (H) x 70° (V) x 120° (D)
Aperture	f/2
TV Distortion	<4.8%

System Requirements

Supported OS	Windows 10 - 64 bit Ubuntu 16.04/18.04 - 64 bit Debian, CentOS (via Docker) Jetson L4T Dual-core ≥ 2.4GHz processor Minimum 4GB RAM
GPU	NVIDIA GPU ≥ 2GB Memory NVIDIA Compute capability ≥ 3.0
Compatible with	NVIDIA Jetson Nano NVIDIA Jetson TX2 NVIDIA Jetson Xavier

Motion / Environmental Sensors

Inertial Measurement Unit	
Accelerometer Range	+/- 8G
Accelerometer Resolution	0.244 mg
Accelerometer Noise Density	3.2 mg
Gyroscope Range	+/- 1000 dps
Gyroscope Resolution	0.03 dps
Gyroscope Noise Density	0.16 dps
Sensitivity Error	+/- 0.4%
Output Data Rate	400 Hz

Magnetometer

Magnetic Field Range	+/- 2500 µT (z) +/- 1300 µT (x,y)
Magnetic Field Resolution	0.3 µT
Output Data Rate	50 Hz

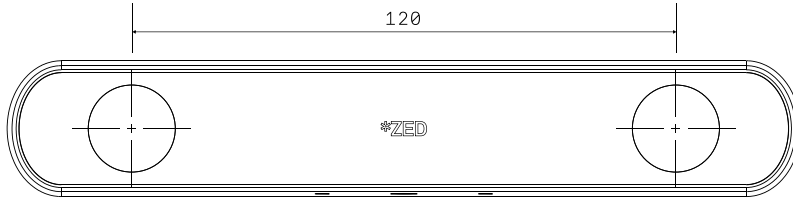
Barometer

Pressure Range	300 to 1100 hPa
Pressure Resolution	0.18 Pa
Relative Pressure Accuracy	0.12 hPa
RMS Noise	0.2 Pa
Output Data Rate	25 Hz

Temperature Sensors

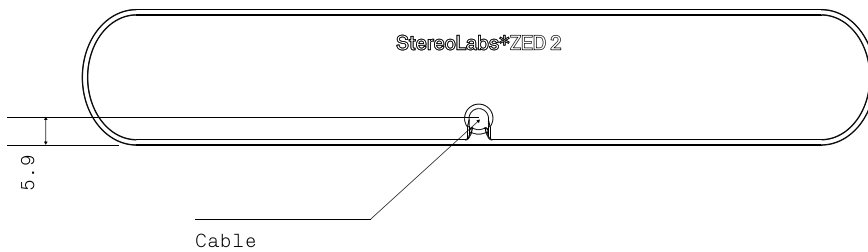
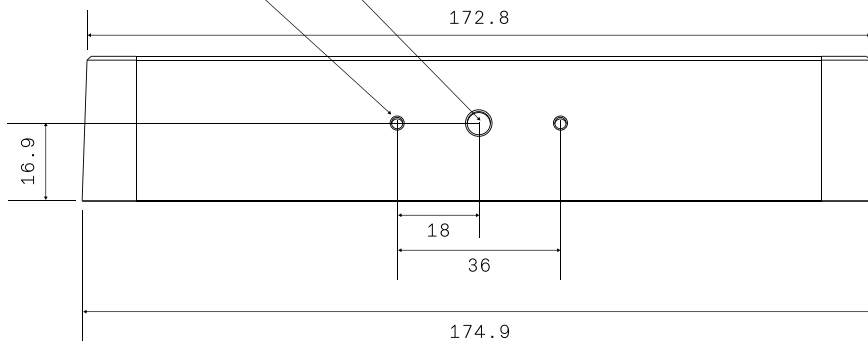
Temperature Range	-40 to 125°C (-40 to 257°F)
Abs. Temperature Accuracy	+/- 0.5°C
Output Data Rate	25 Hz

*ZED 2 Technical Drawings



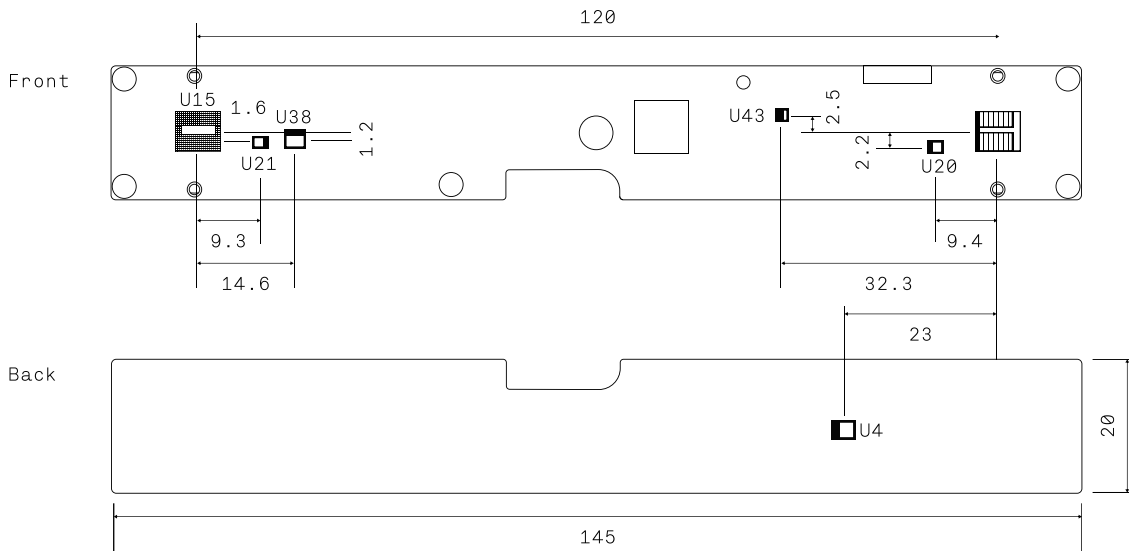
1x
Mounting hole
1/4-20 UNC
Max Length:7mm

2x
Mounting holes
M3x0.5
Max Length:10mm



*ZED 2 Technical Drawings

Sensors Diagram



U4	IMU - Accelerometer	U21	Temperature Sensor Right
U12	Image Sensor Left	U38	Barometer
U16	Image Sensor Right	U43	Magnetometer
U20	Temperature Sensor Left		